

Wing Flutter Computation Using Modified Spectral Volume Method

Yuta SAWAKI
Department of Aerospace Engineering
Tohoku University

Outline

- Background
- Objective
- Spatial discretization method
- Validation of present code
 - Unsteady flowfield over NACA0012 airfoil in pitching motion
- Flutter computation
 - AGARD445.5 weakened wing
- Summary
- Future works

Transonic Flutter

- Self oscillation caused by aerodynamic, elastic and inertial forces
- Easy to occur in case of high aspect ratio, thin wing and low stiffness material
- Wing may be broken

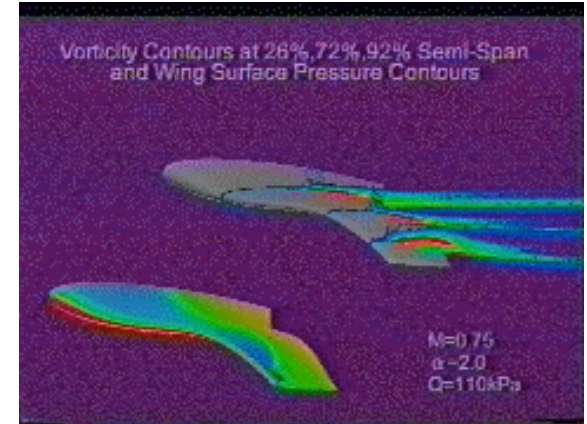
using composite materials



stiffness decreases

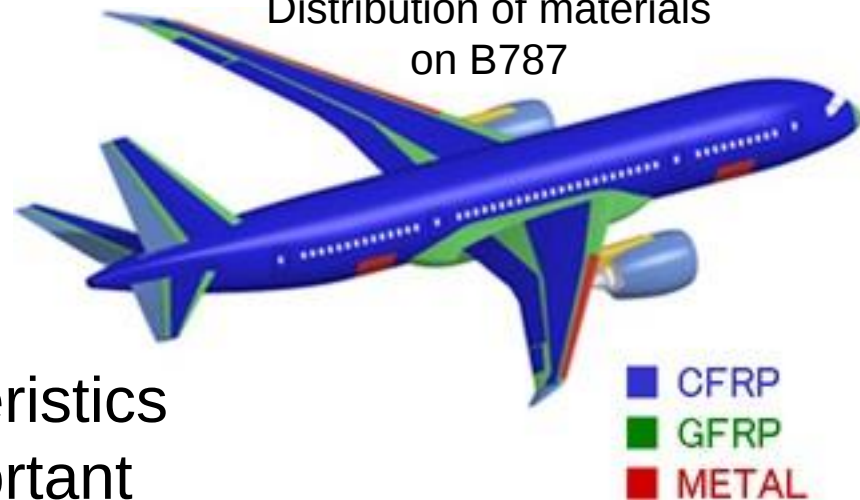
Examination of flutter characteristics is getting more and more important

Numerical flutter analysis by JAXA



<http://www.aero.jaxa.jp/research/kitai/ki-kuuriki.html>

Distribution of materials
on B787



<http://www.mech.nias.ac.jp>

Examination of Flutter Characteristics

- Wind tunnel test
- **Numerical analysis**

Analysis assuming **linear** aerodynamic force

- Cannot consider shock wave
- Computational cost is lower



Pursue performance
with flutter margin

Analysis assuming **non-linear** aerodynamic force

- Can consider shock wave
- Computational cost is higher
- Reduce number of wind tunnel tests

Objective

- Develop fluid-structure interaction code
 - CFD code development
 - ALE formulation for moving grid
 - Extend conventional SV method to hybrid unstructured mesh
 - Code validation
 - Unsteady flowfield over NACA0012 airfoil in pitching motion
 - Flutter computation
 - AGARD445.6 weakened wing

Conventional Spectral Volume Method

- Finite volume method
- High order unstructured grid method

Tetrahedral cell (= Spectral Volume (SV))

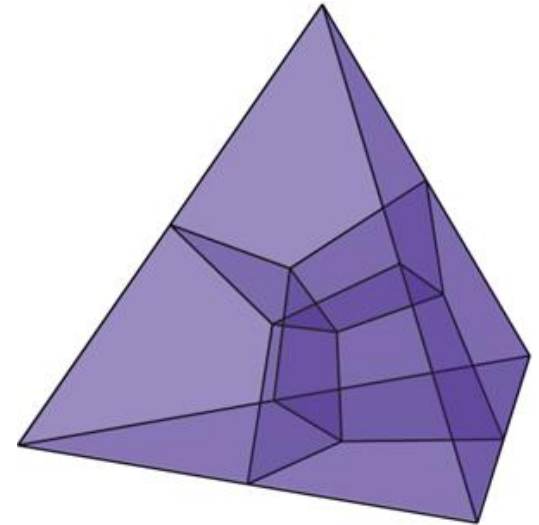
 **Further subdivided**

4 hexahedral cells (= Control Volume (CV))

- Governing equations are solved in each CV
- Distribution of variables in SV is written by high order polynomial consists of 4 CV cell average values

Reconstructed polynomial: $\tilde{Q}(\xi, \eta, \zeta) = \sum_j^4 L_j(\xi, \eta, \zeta) \underline{\bar{Q}_j}$

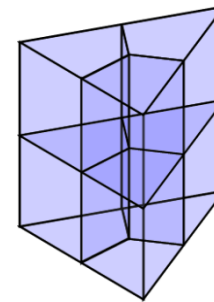
Shape function: $L_j(\xi, \eta, \zeta) = c_j^1 \xi + c_j^2 \eta + c_j^3 \zeta + c_j^4$



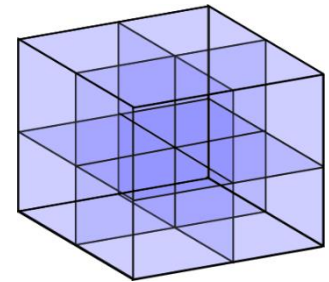
Tetrahedron
4DOFs

Modified SV Method for Flutter Analysis

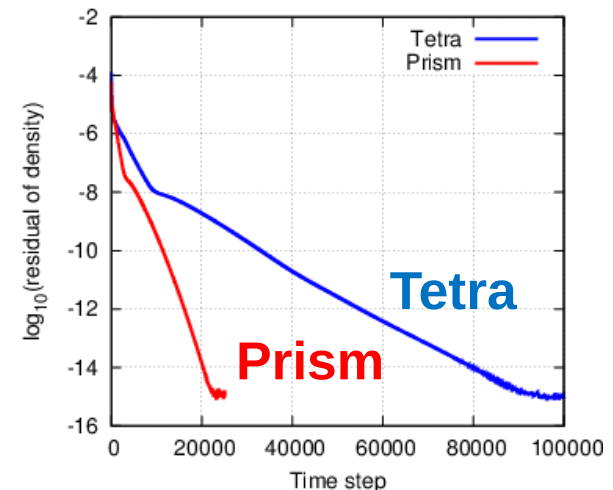
- Arbitrary Lagrangian-Eulerian (ALE) formulation for moving grid
- Extended to utilize **hybrid** unstructured meshes
 - Conventional SV utilizes **only tetrahedral cells (4DOFs)**
 - Although number of DOFs is increased in each cell other than tetrahedral cells, the total number of computational cells can be substantially reduced
 - **Convergence rate** is significantly improved by introducing prismatic cell layers on the solid wall
 - Truly second order even for skewed unstructured meshes
 - Adaptive mesh refinement is easily devised by hierarchical subdivision of control volume



**Prism
6DOFs**



**Hexahedron
8DOFs**



**Convergence histories
for turbulent boundary
layer over flat plate**

Validation of Present Code on Moving Grid

- Unsteady flowfield over NACA0012 airfoil in pitching motion
 - Compared with Landon's experiment

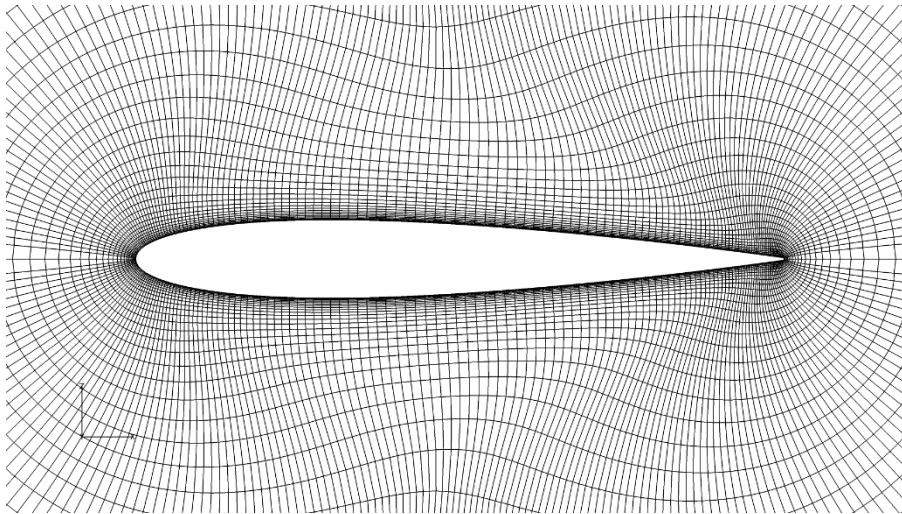
Numerical Methods

Governing equations	: 3D Euler/RANS equations
Spatial discretization	: 2nd order modified SV method
Numerical flux	: SLAU
Viscous term gradient	: BR2 method
Time integration	: 2nd order backward difference formula (BDF2)
Implicit method	: LU-SGS method with inner iteration
Turbulence model	: Spalart-Allmaras model

Computational Grids

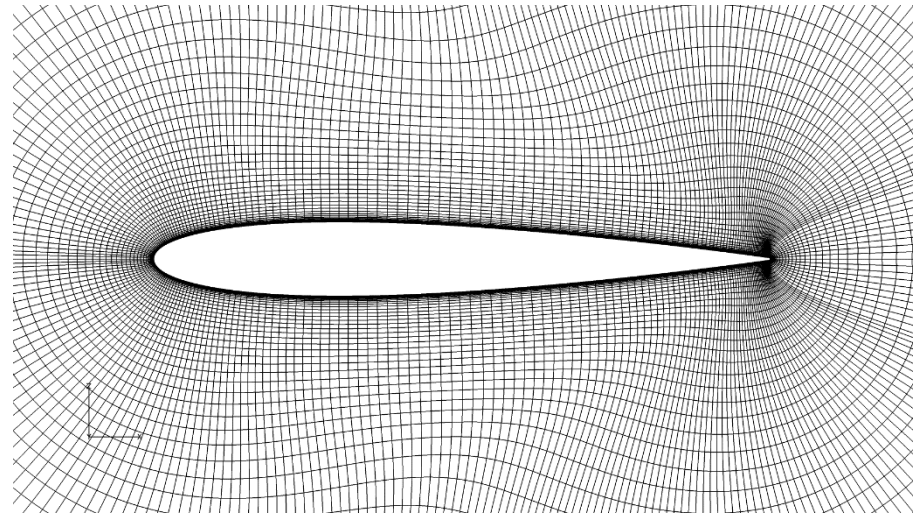
➤ Euler

- Hexahedrons: 19,720
- Computational domain: 30 chord



➤ RANS

- Hexahedrons: 28,500
- Computational domain: 30 chord
- Off wall spacing: 5.6×10^{-6}
($y^+ = 1$)



Computational Conditions

➤ Free stream condition

- Mach number: 0.6
- Reynolds number: 4.8×10^6

➤ Criteria for ending inner iteration

- $\Delta\rho < 10^{-7}$

➤ Δt , CFL, inner iterations

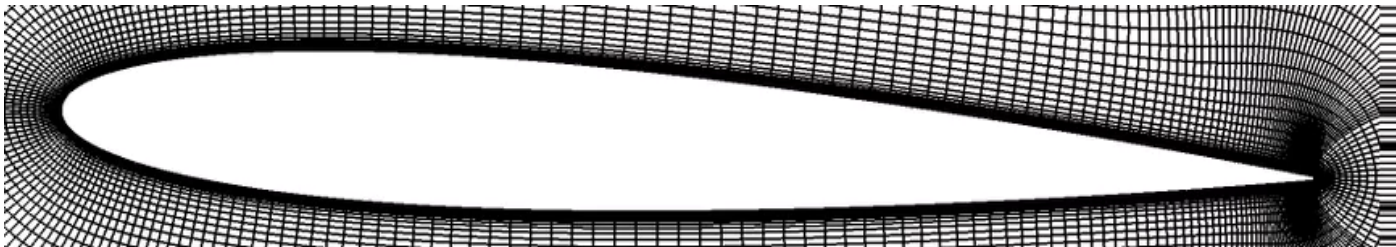
	CFL (Δt)	Inner iteration
Euler	300 (0.05)	25
RANS	23,000 (0.05)	50

➤ Pitching condition

- Pitching center: 25% of chord
- AoA: $\alpha = \alpha_m + \alpha_0 \sin(\omega t)$
 - Mean AoA: $\alpha_m = 2.89[\text{deg.}]$
 - Amplitude: $\alpha_0 = 2.41[\text{deg.}]$
 - Non-dimensional frequency:

$$k = 0.0808$$

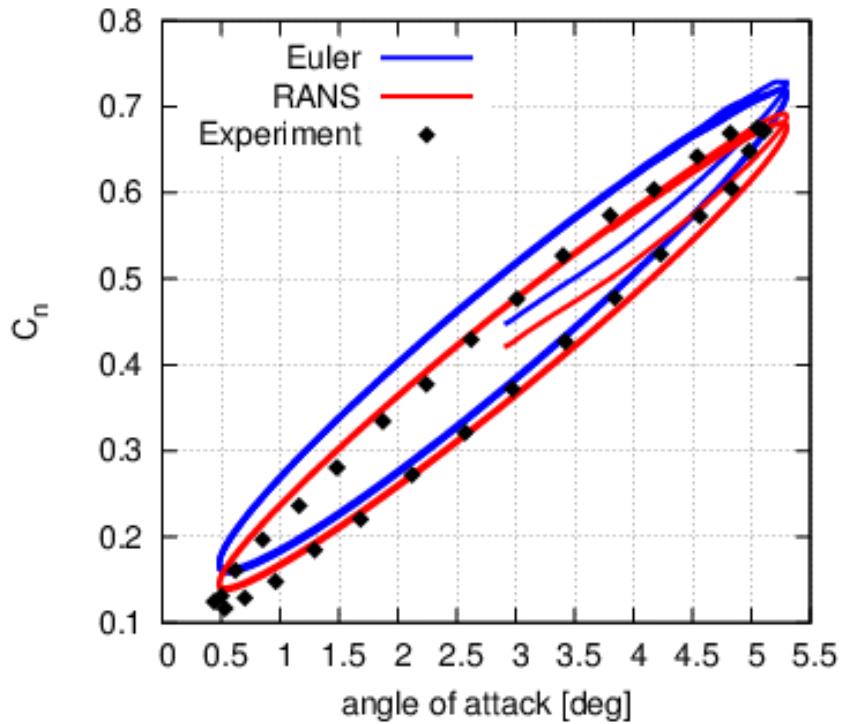
$$k = \frac{\omega c}{2U_\infty} \quad \begin{array}{l} \omega : \text{frequency} \quad c : \text{chord} \\ U_\infty : \text{free stream velocity} \end{array}$$



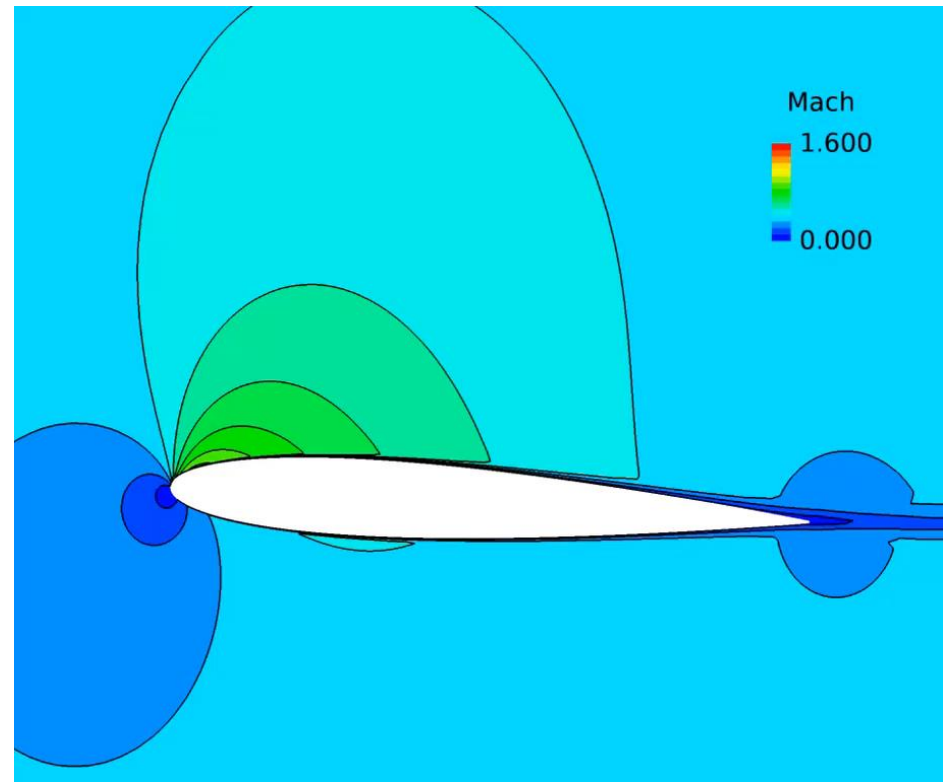
Pitching motion

Results

$C_n - \alpha$ hysteresis loop



Mach contours (RANS)



Flutter Computation Using Fluid-Structure Interaction Code

- Flutter prediction for AGARD445.6
weakened wing
 - Compared with Yates's experiment

Numerical Methods

➤ Fluid analysis

Governing equations : 3D Euler/RANS equations

Time integration : BDF2 (implicit)

➤ Structure analysis

Governing equation : Equation of motion using modal analysis

Mode analysis : 1st – 5th mode

Modal damping ratio : 0.02

Time integration : BDF2 (implicit)

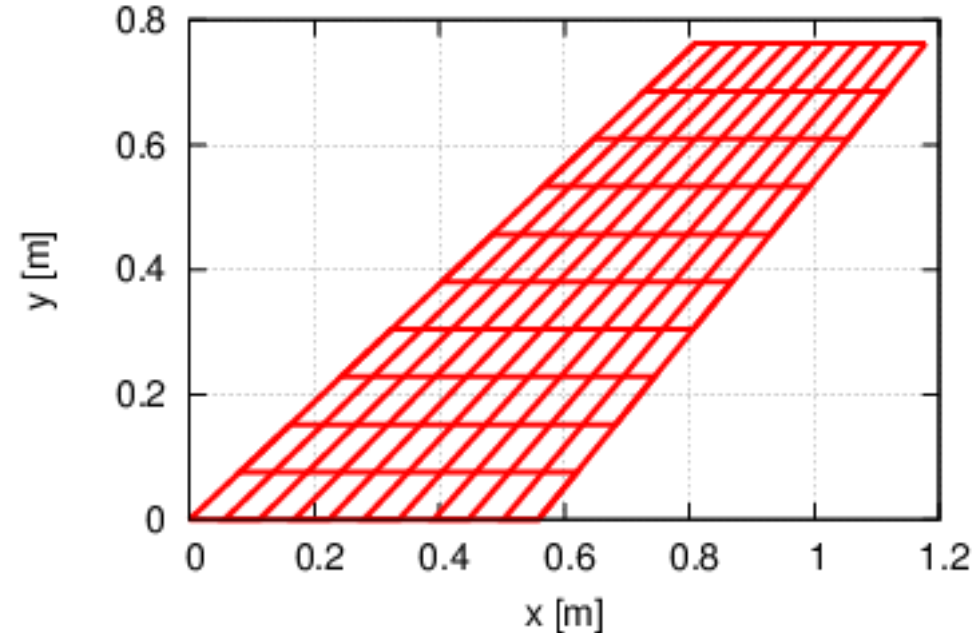
➤ Grid deformation

Interpolation method using function weighted by inverse distance

AGARD445.6 Wing Structure Model

➤ Wing size

- Root chord : 0.558 [m]
- Span : 0.762 [m]
- Aspect ratio : 1.65
- Taper ratio : 0.66
- Sweepback : 45 [deg.]
- Airfoil : NACA65A004



➤ Yates's model*

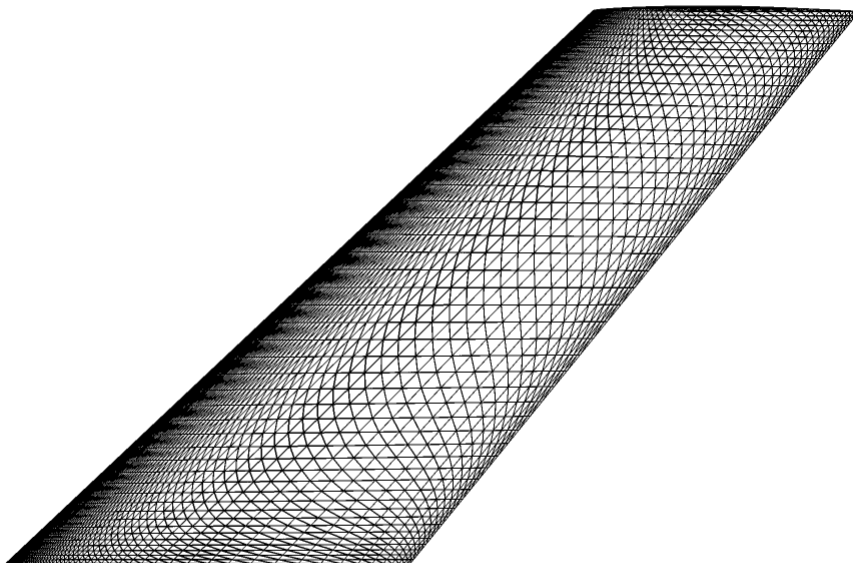
Mode		1st (bend)	2nd (torsion)	3rd (bend)	4th (torsion)	5th (bend)
Eigen frequency [Hz]	Computational data (Yates)	9.6	38.2	48.3	91.5	118.1
	Experimental data	9.6	38.1	50.7	98.5	-

* E. Carson Yates Jr., "AGARD Standard Aeroelastic Configuration for Dynamic Response I-Wing 445.6", NASA TM 100492, 1987

Computational Grids

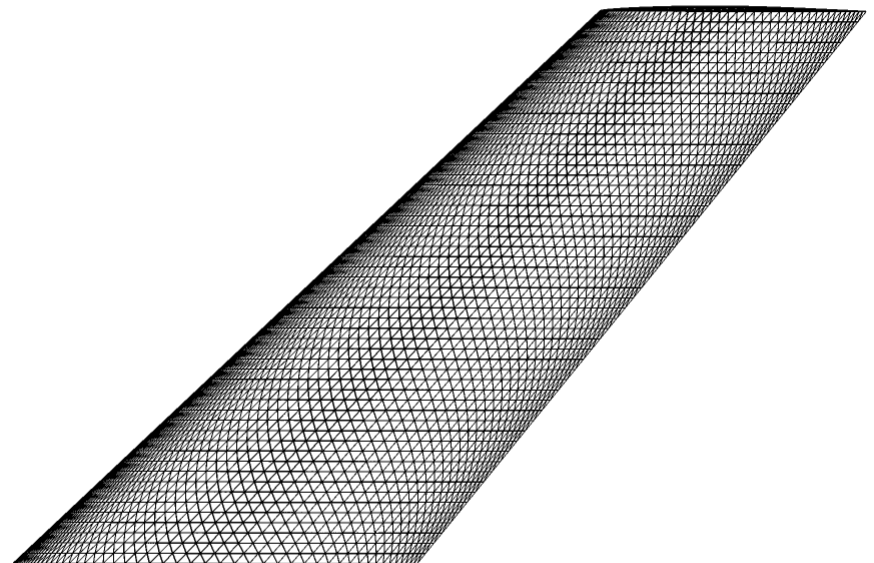
➤ Euler

- Tetrahedrons: 190,436
- Computational domain: 30 MAC



➤ RANS

- Tetrahedrons: 178,278
- Prisms: 310,464
- Computational domain: 30 MAC
- Off wall spacing: 2.4×10^{-5}
($y^+ \leq 2$)



Computational Conditions

➤ Free stream condition

- Mach number: 0.499, 0.678, 0.901, 0.960, 1.072, 1.141
- AoA: 0.0 [deg.]

➤ Initial condition

- Steady flow field solution
- Tiny oscillation assumed in the 1st bending mode

➤ Criteria for ending inner iteration

- $\Delta\rho < 10^{-7}$

➤ CFL number, Δt , inner iteration

	CFL (Δt)	Inner iteration
Euler	50 (0.0075)	8
RANS	400,000 (0.05)	20

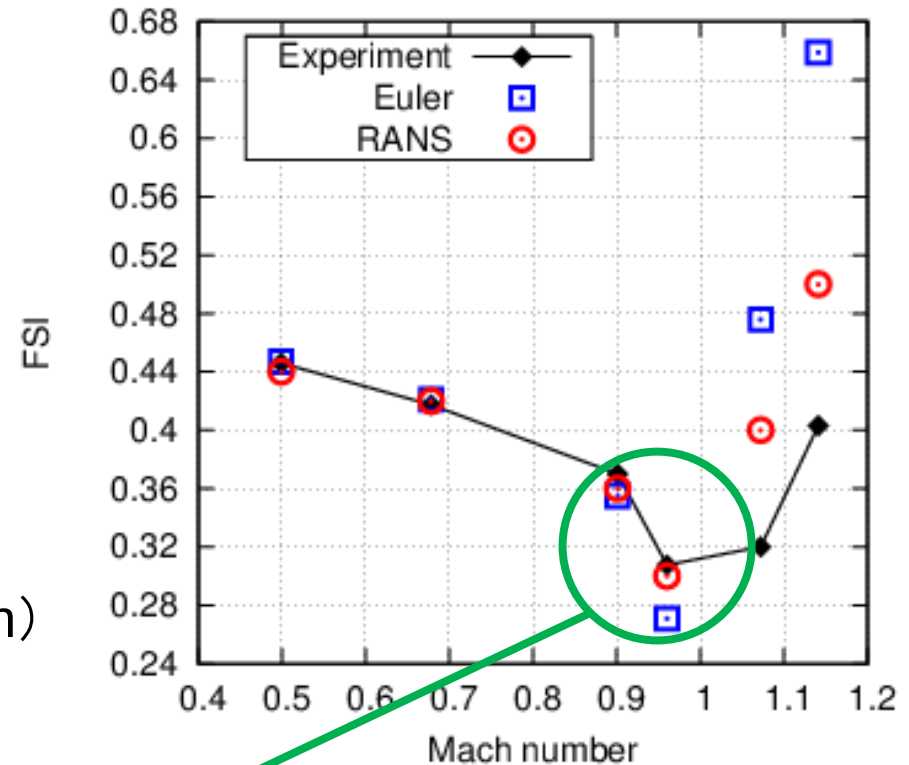
Comparison of Flutter boundary

Flutter Speed Index (FSI)

$$FSI = \frac{U_{\infty}}{b_s \omega_{\alpha} \sqrt{\bar{\mu}}}$$

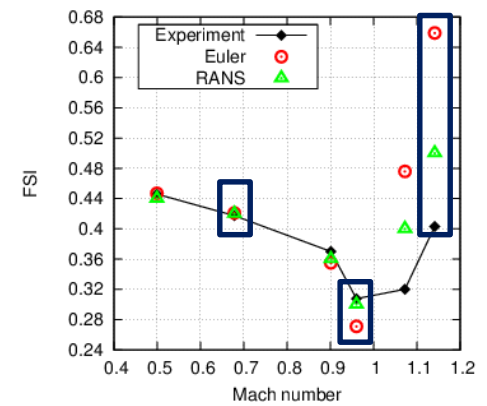
$$\bar{\mu} = \frac{\bar{m}}{\rho_{\infty} v}$$

- U_{∞} : Free stream velocity
- b_s : Half root chord
- ω_{α} : Eigen frequency (1st torsion)
- $\bar{\mu}$: mass ratio
- $\bar{m}$: Wing model mass
- ρ_{∞} : Free stream density
- v : Truncated cone volume



Transonic dip

Distribution of C_p on wing surface

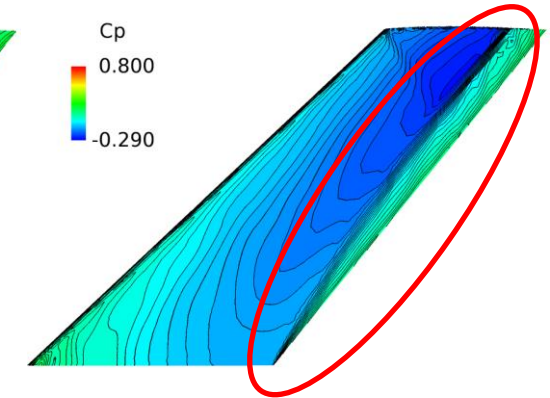
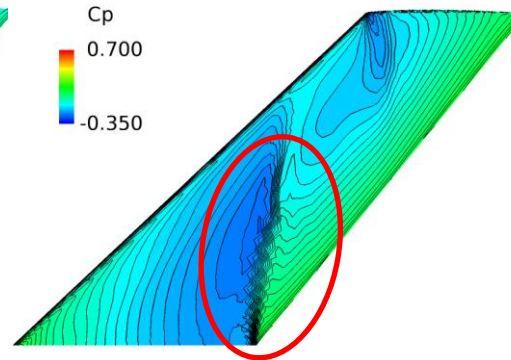
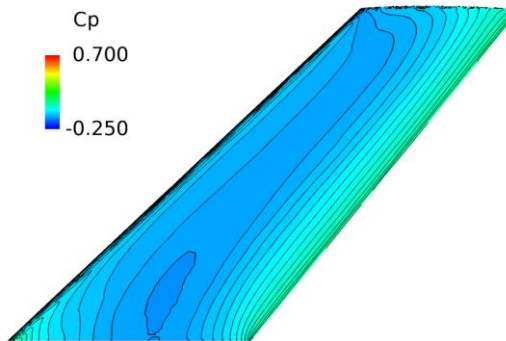


M=0.678

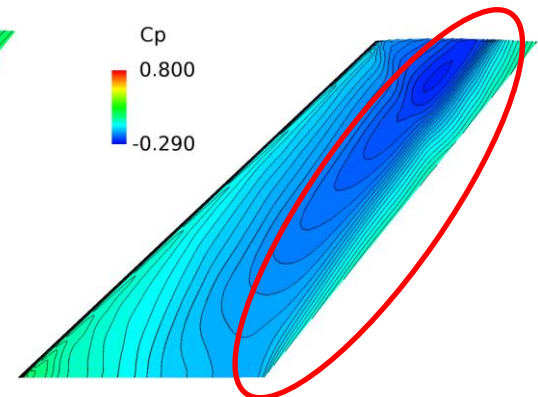
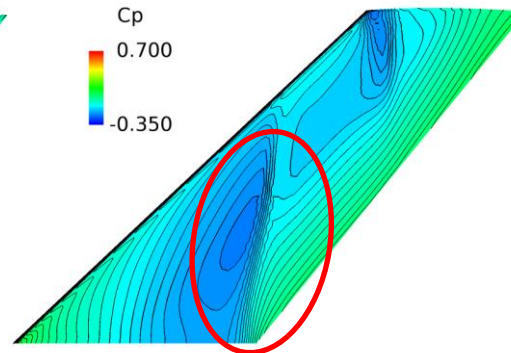
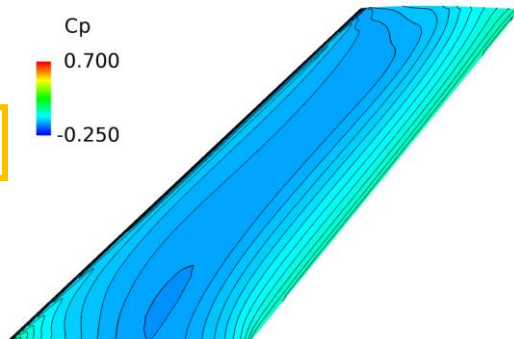
M=0.960

M=1.141

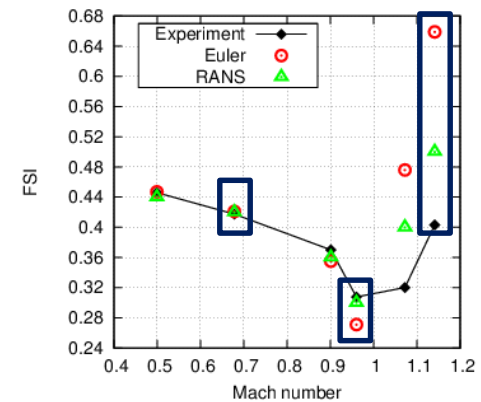
Euler



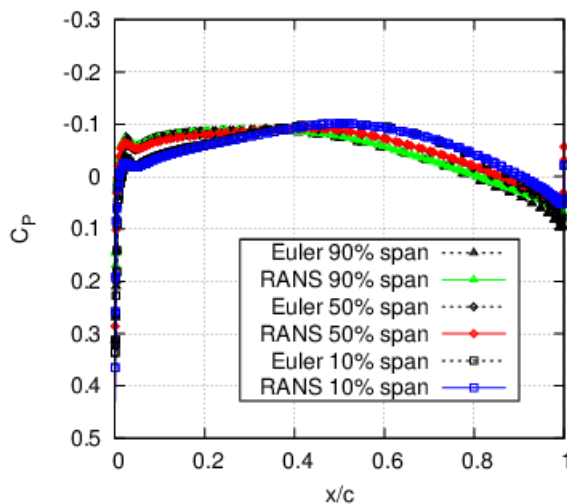
RANS



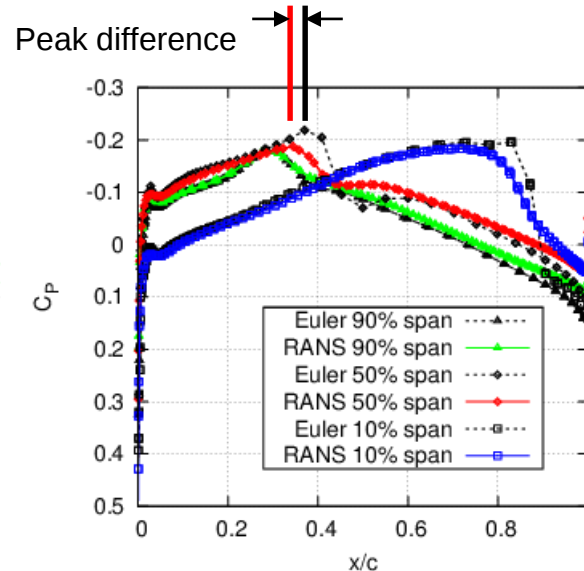
Distribution of C_p on several cross sections



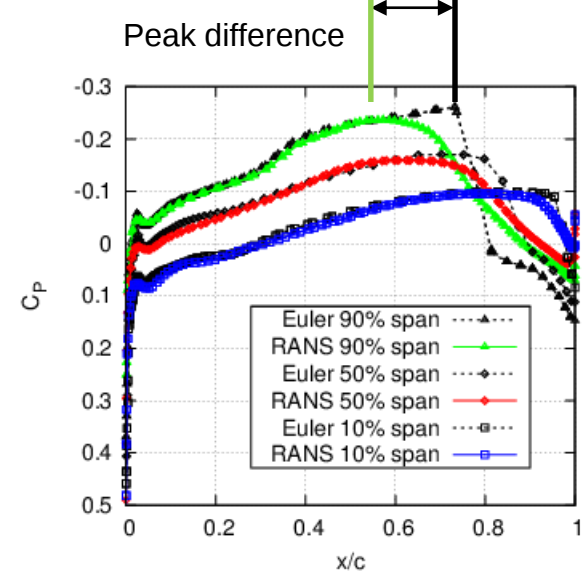
M=0.678



M=0.960



M=1.141



- More dissipative shock wave in RANS
- Large Peak difference of negative C_p at supersonic

Summary

- SV code is successfully extended to include:
 - ALE formulation
 - Unstructured hybrid meshes
- Code validation study for flowfield over NACA0012 airfoil in pitching motion
 - C_n hysteresis loop is successfully reproduced when viscous effect is taken into account
- Fluid-structure interaction code is developed to consider AGARD445.6 weakened wing
 - Flutter boundary is reproduced for subsonic cases
 - Transonic dip phenomenon is well reproduced
 - Consideration of viscous effect obviously improves flutter boundary prediction at supersonic freestream, though some distinctions are yet remained

Future Works

- Further study for AGARD445.6 wing flutter at supersonic freestream
 - Is RANS simulation adequate for quantitative prediction ?
 - Do we need to employ LES or DES ?
 - Is consideration of boundary layer transition necessary ?
- Examine several aeroelastic problems chosen from AIAA Aeroelastic Prediction Workshop for improving numerical methods
- Consideration of wing flutter with engines mounted on wing